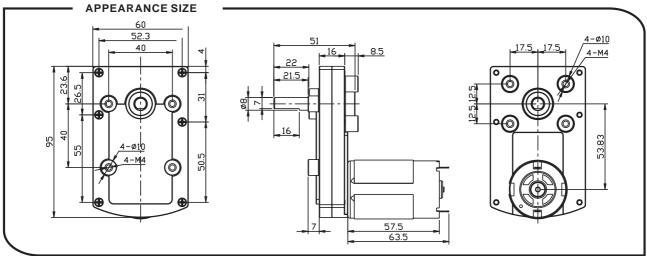
# **DC Gear Motor**

## TT-555 DC GEAR MOTOR Series





#### Gearbox data:

Number of stages	3 stages reduction	4 stages reduction	5 stages reduction					
Reduction ratio	36、66、94	149、196、211、277、394	624、830、1166					
Max. Running torque	5Kgf ⋅ cm	20Kgf • cm	50Kgf • cm					
Max. Gear breaking torque	15Kgf ⋅ cm	60Kgf • cm	150Kgf ⋅ cm					
Max.Gearing efficiency	73%	65%	59%					
Other reduction ratio please telephone or e-mail to our engineering department.								

### Motor data:

Motor name	Rated Volt. V	No load		Load torque			Stall torque		
		Current	Speed	Current	Speed	Torque	Output power	Torque	Current
		mA	r/min	mA	r/min	gf • cm	W	gf • cm	mA
RS-555123000	12	≤140	3000	≪800	2200	150	3.3	600	3000
RS-555124500	12	≤220	4500	≤1200	3300	220	7.2	880	4800
RS-555126000	12	≤350	6000	≤2000	4500	300	13.5	1200	6000
RS-555243000	24	≤70	3000	≤400	2200	150	3.3	600	1600
RS-555244500	24	≤110	4500	≤600	3300	220	7.2	880	3000
RS-555246000	24	≤180	6000	≤1000	4500	300	13.5	1200	4000

<sup>1.</sup> This table lists some motors parameters, others please refer to specific parameters of Page 148.

#### NOTE:

- 1. Gearmotor named methods: e.g. TT-555123000-94K Motor please refer to the motor data RS-555123000.Gearbox please refer to gearbox data reduction ratio 94.Related to gearmotor output speed and torque please refer to motor data.
- 2. Motor can be installed with magnetic encorder, encorder parameters please refer to Page 141.
- 3、Gearbox shell material:zinc alloy.
- 4. Gearbox gear materials: The first stage gear:plastic gear. The final stage gear: 45 # steel Heat-treatment gear. Other stages gear:powder metallurgy gear.
- 5 Standard output shaft after reducing:  $\Phi 8.0$ mm. other sizes of the output shaft can make as client request.
- 6. Chart only for reference, products shall prevail the entity.

<sup>2.</sup> After connecting motor and gearbox which isnamed gearmotor the output torque:motor torque X reduction ratio X gearing efficiency;output speed:motor speed/reduction ratio.